



6 Axis 20kg Payload 1650mm Reach

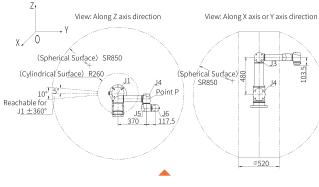
Learn More



www.aubo-usa.com

Joint 4 Joint 6 Joint 5 Joint 3 Joint 2 Joint 1

The AUBO i20s medleys the best of safety and precision from collaborative robots with all of the toughness you'd expect from an industrial robot. The i20s' power force limiting technology coupled with a smaller footprint makes it the perfect high-tier performance automation solution while retaining collaborative capabilities. The AUBO i20s is designed for a wide range of heavy-duty applications but excels in applications that demand extra performance like palletizing, packaging, and load-carrying.



WORKSPACE DIMENSIONS

SPECIFICATIONS

Payload	20 kg	
Reach	1650 mm	
Weight	63 kg	
Mounting Base Footprint	Ø260 mm	
Avg. Power Consumption	1000 W	
Peak Power Consumption	3000 W	
Operating Temperature	0-50 °C	
Humidity	90% Relative Humidity (No Condensation)	

CONTROL BOX SPECIFICATIONS

Size (L x W x H)	390mm x 370mm x 265mm
Weight	15 kg
Robot Cable Length (Customizable)	5 m
Teach Pendant Cable Length	4 m
Power Supply Cable Length	5 m
Communication Protocols	Ethernet TCP/IP, ModBus-RTU/TCP, Profinet
	I/O Ports
Digital Input	16 (User) / 16 (Safety)
Digital Output	16 (User) / 16 (Safety)
Analog Input	4
Analog Output	4
I/O Power Supply	24V 3A
Power Supply Requirements	100-240VAC, 50-60Hz
Open Source Development Support	SDKs in C/C++/C#/Lua/Python, ROS, Plug-in Support

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MOVEMENT

Repeatability (ISO 9283) ±0.1 mr					
Tool Velocity		≤2.6 m/s			
Axis Movement	Working Range	Maximum Speed			
J1 Base	±360 °	93 °/s			
J2 Shoulder	±360 °	93 °/s			
J3 Elbow	±360 °	178 °/s			
J4 Wrist	±360 °	178 °/s			
J5 Wrist	±360 °	178 °/s			
J6 Wrist	±360 °	178 °/s			

AUBO i20s

FEATURES

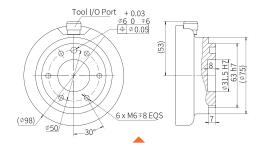
Mounting Orientation	Any Orientation			
IP Classification	IP 54			
ISO 1644-1 Clean Room Level	Class 5			
Tool I/O Ports				
Digital Input	4 (Customizable)			
Digital Output	4 (Customizable)			
Analog Input	2			
Analog Output	-			

I/O Power Supply			
Output Voltage	0V/12V/24V		
Output Current	0.8A		

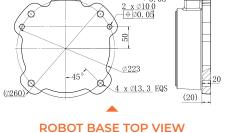
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END FLANGE DIMENSIONS



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PRODUCT DIMENSIONS		
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